

# Kian Abbott

✉ contact@kianabbott.com | 🌐 www.kianabbott.com | 🔗 LinkedIn | 📍 East Setauket, NY

## EDUCATION

---

### Harvard University

Cambridge, MA

*S.B. in Electrical Engineering; GPA: 3.28/4.00*

*September 2019 – December 2023*

Coursework in Circuits and Transduction, Computer Architecture, Computing Hardware, Solid State Circuits, Systems Programming, Signals and Systems, Electronic and Photonic Devices, Nanofabrication, VLSI Circuits, Electromagnetism.

## SKILLS

---

**Hardware Design:** Proficient in SystemVerilog, Altium Designer, LTSpice. Knowledge of Cadence Virtuoso.

**Programming:** Proficient in C, C++, Python, MATLAB, Arduino. Knowledge of: Git, Bash, SQL, GDB.

**Web Design:** Proficient in JavaScript. Knowledge of: HTML, CSS, Markdown, Jekyll.

## EXPERIENCE

---

### Portal XR

Remote

*Founding Engineer*

*May 2022 – October 2025*

- Architected and implemented in SystemVerilog an Arty A7 based controller for a 30kHz resonant mode, two-axis scanning micro-electromechanical system (MEMS) mirror laser display.
- Engineered an analog front end to generate current controls and isolate a feedback signal for mirror actuation.
- Designed and assembled connecting PCBs including a 4-layer board hosting the analog front end, and interposing boards for mating with the MEMS mirror.

### Second Order Effects

Redmond, WA

*Engineering Intern*

*June 2022 – December 2022*

- Executed the layout of a mixed-signal engine controller printed circuit board (PCB) for a client pre-preliminary design review, which achieved a component placement density of over 50%.
- Reduced processing system resource usage in a Zynq Ultrascale+ Multi-Processor System on Chip (MPSoC) by moving the SPI driver for a motor controller to programmable logic, and accordingly updating C++ drivers.
- Debugged and verified the functionality of a thermal control test unit in preparation for client demonstration.
- Soldered CAN bus harnessing and installed emergency stop switches on a prototype agricultural robot.
- Compiled flight controller (FC) market research, which contributed to acquiring an electric vertical takeoff and landing FC design contract.

### Harvard University

Cambridge, MA

*Course Assistant*

*January – May 2021, 2022, 2023*

- Clarified course material and offered tutoring on problem sets for over 70 students in Engineering Sciences 50: Introduction to Electrical Engineering.
- Debugged circuits using standard bench-top equipment (oscilloscope, digital multimeter, power supply, function generator), and provided technical support in Arduino and MATLAB coding during weekly lab sessions.
- Advised teams of 2 to 4 students in the ideation and realization of final projects on topics including gesture-commanded robotics and feedback-controlled instrument tuning.

### Edge Computing Lab

Remote and Cambridge, MA

*Project Assistant*

*May 2021 – December 2021*

- Tested deployment of a 2D convolution custom function unit which resulted in a 53% decrease in the number of cycles spent running inference on a field programmable gate array (FPGA).
- Optimized the performance of a depthwise convolution through software and hardware which resulted in a 47% decrease in the number of cycles spent running inference on an FPGA.

## PROJECTS

---

### NASA JPL Europa Clipper: CaliPER CubeSat

*December 2022 – December 2023*

- Designed a state-driven cube satellite (CubeSat) thruster and attitude controller system capable of orienting, guiding, and dumping accumulated momentum based on inertial measurement unit (IMU) readings.
- Evaluated the controller and state machine against 7 key specifications in a MATLAB/Simulink environment.
- Documented the research, specification creation, design, and test processes in a technical report and presentation.
- Worked in collaboration with 11 engineering students, interfacing primarily between the propulsion and guidance, navigation, and control (GNC) hardware design teams.

### Multi-cycle Processor RTL

*April 2021*

- Developed the register transfer level (RTL) description of a MIPS processor supporting 23 instructions in SystemVerilog and verified the design through a testbench executing test assembly programs.